

### Abstract

Proper orthogonal decomposition (POD) is a widely-used model order reduction technique for the computation of surrogate reduced state spaces from given solution snapshot data. However, performing a POD is often a computationally demanding task since the complexity relates quadratically to the number of snapshots.

A nearby solution to overcome this limitation is to compute, when and where available, PODs of subsets of the global snapshot set, and then to use the resulting POD modes

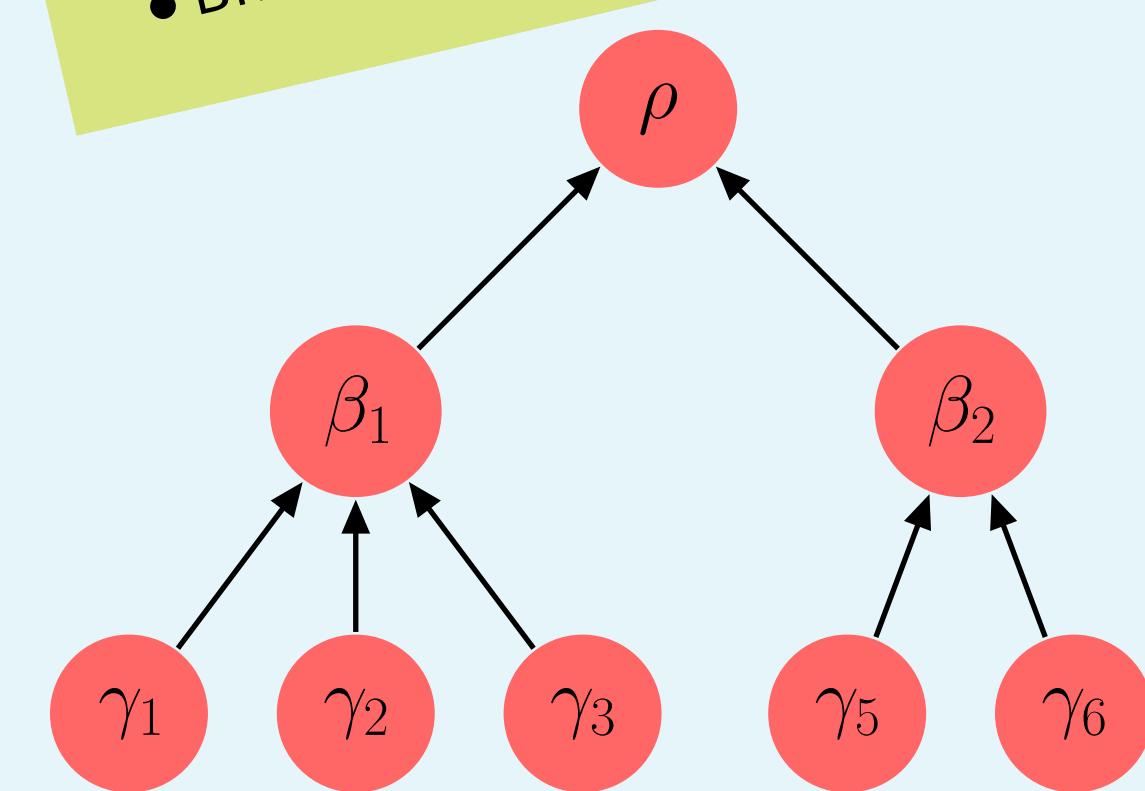
as input for an additional POD. We formalise this approach as “hierarchical approximate POD” (HAPOD), allowing arbitrary trees of localized PODs, making HAPOD suitable for distributed, heterogeneous compute environments.

As special cases of the HAPOD we consider a “distributed approximate POD” (DAPOD) and a “rolling approximate POD” (RAPOD), for which we present numerical results for a model reduction benchmark problem.

## HAPOD – Hierarchical Approximate POD

HAPOD can be easily implemented on top of any existing POD code. Given a set  $\mathcal{S}$  of snapshot vectors, we assume that  $\text{POD}(\mathcal{S}, \varepsilon)$  computes the first  $N$  POD mode / singular value pairs such that:

- $\mathcal{O}(|\mathcal{S}|^2) \rightarrow \mathcal{O}(|\mathcal{S}| \log(|\mathcal{S}|))!$
- Cloud-friendly!
- Bring-your-own-SVD!



#### HAPOD Input:

$\gamma_i$ : snapshot vectors  $\mathcal{S}_{\gamma_i}$   
 $\beta_i$ : outputs of child nodes  
 $\rho$ : outputs of child nodes

#### Abstract Error Bound:

$$\left( \frac{1}{|\mathcal{S}|} \sum_{s \in \mathcal{S}} \|s - P(s)\|^2 \right)^{1/2} \leq \sum_{l=1}^L \max_{L(\alpha)=l} \frac{\sqrt{M_\alpha}}{\sqrt{|\mathcal{S}_\alpha|}} \cdot \varepsilon(\alpha)$$

#### HAPOD Output:

$\gamma_i$ :  $\text{POD}(\text{input}, \varepsilon(\gamma_i))$  scaled by singular values (pass input if  $\varepsilon(\gamma_i) = 0$ )  
 $\beta_i$ :  $\text{POD}(\text{input}, \varepsilon(\beta_i))$  scaled by singular values  
 $\rho$ :  $\text{POD}(\text{input}, \varepsilon(\rho))$

#### Abstract Mode Bound:

$$|\text{HAPOD}(\mathcal{S}, \rho, \varepsilon)| \leq \left| \text{POD}\left(\mathcal{S}, \frac{\sqrt{M_\rho}}{\sqrt{|\mathcal{S}|}} \cdot \varepsilon(\rho) - \sum_{l=1}^{L-1} \max_{L(\alpha)=l} \frac{\sqrt{M_\alpha}}{\sqrt{|\mathcal{S}_\alpha|}} \cdot \varepsilon(\alpha) \right) \right|$$

#### Choice of Error Tolerances:

$$\varepsilon(\rho) := \frac{\sqrt{|\mathcal{S}|}}{\sqrt{M_\rho}} \cdot (1 - \omega) \cdot \varepsilon^*, \quad \varepsilon(\alpha) := \frac{\sqrt{|\mathcal{S}_\alpha|}}{\sqrt{M_\alpha(L-1)}} \cdot \omega \cdot \varepsilon^*$$

#### Error Bound:

$$\left( \frac{1}{|\mathcal{S}|} \sum_{s \in \mathcal{S}} \|s - P(s)\|^2 \right)^{1/2} \leq \varepsilon^*$$

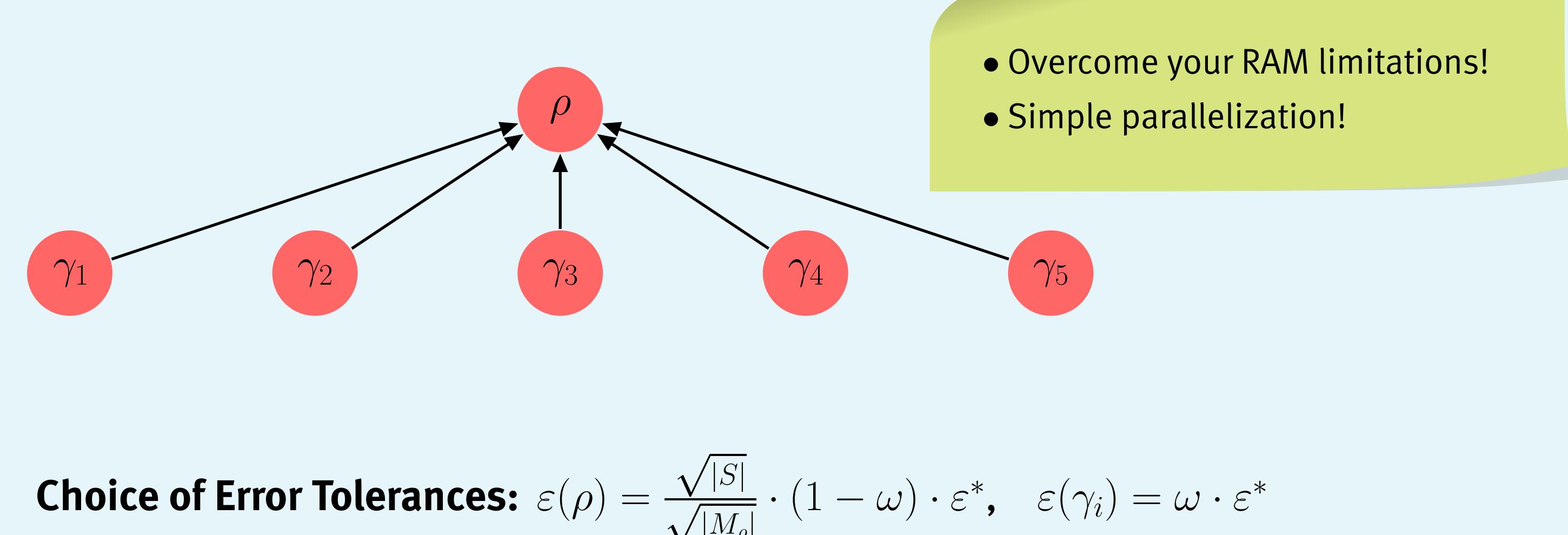
#### Mode Bound:

$$|\text{HAPOD}(\mathcal{S}, \rho, \varepsilon)| \leq |\text{POD}(\mathcal{S}, (1 - 2\omega) \cdot \varepsilon^*)|$$

#### Notation:

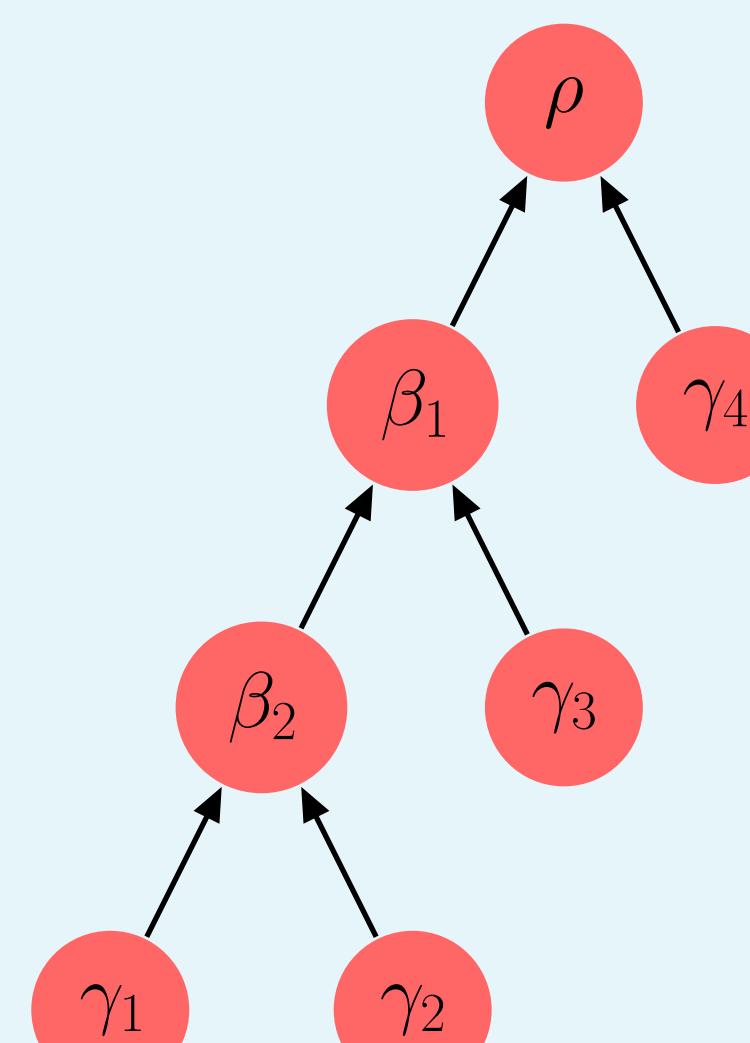
$\mathcal{S}_\alpha$ : snapshots below  $\alpha$   
 $M_\alpha$ : POD modes at  $\alpha$   
 $L$ : depth of tree  
 $L(\alpha)$ : depth of  $\alpha$   
 $P$ : projection onto HAPOD mode space at  $\rho$   
 $\omega$ : parameter  $\in (0, 1/2)$

## DAPOD – Distributed Approximate POD



Choice of Error Tolerances:  $\varepsilon(\rho) = \frac{\sqrt{|\mathcal{S}|}}{\sqrt{M_\rho}} \cdot (1 - \omega) \cdot \varepsilon^*, \quad \varepsilon(\gamma_i) = \omega \cdot \varepsilon^*$

## RAPOD – Rolling Approximate POD



#### Choice of Error Tolerances:

$$\begin{aligned} \varepsilon(\rho) &= \frac{\sqrt{|\mathcal{S}|}}{\sqrt{M_\rho}} \cdot (1 - \omega) \cdot \varepsilon^* & \varepsilon(\beta_i) &= \frac{\sqrt{|\mathcal{S}|}}{\sqrt{M_{\beta_i}} \cdot (L-1)} \cdot \omega \cdot \varepsilon^* \\ \varepsilon(\gamma_1) &= \frac{1}{L-1} \cdot \omega \cdot \varepsilon^* & \varepsilon(\gamma_i) &= 0, \quad i > 1 \end{aligned}$$

- On-the-fly live data compression!
- Fast even when whole trajectory does not fit into RAM!

## Benchmark Problem

#### Synthetic Parametric Model (See MORWIKI: [http://modelreduction.org/index.php/Synthetic\\_parametric\\_model](http://modelreduction.org/index.php/Synthetic_parametric_model))

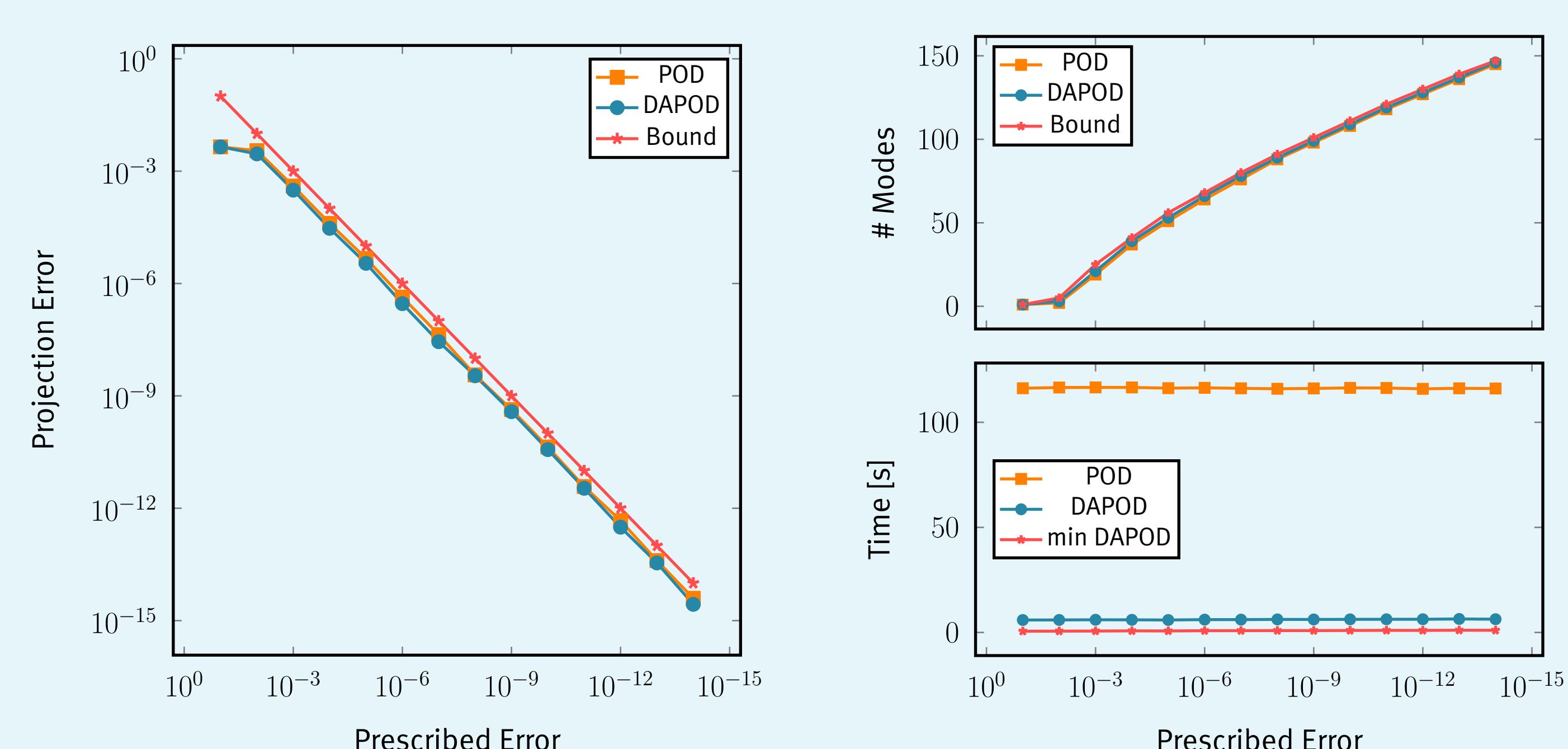
- linear time-invariant
- affine-parametric
- single-input
- $\dim(x(t)) := 10^5$
- $C := 1$
- $\theta \in (0, 1]$
- $u(t) := \delta(t)$
- implicit RK1
- $\mathcal{S}_{\text{DAPOD}} = \{x(t; \theta) \mid \theta = k \cdot 0.1, 1 \leq k \leq 10\}$
- $\mathcal{S}_{\text{RAPOD}} = \{x(t; \theta) \mid \theta = 0.5\}$

## Get the Code



<http://j.mp/morml1>

## DAPOD Numerical Experiment



## RAPOD Numerical Experiment

