



MAX PLANCK INSTITUTE
FOR DYNAMICS OF COMPLEX
TECHNICAL SYSTEMS
MAGDEBURG



COMPUTATIONAL METHODS IN
SYSTEMS AND CONTROL THEORY

If the Mountain Won't Come Reduced Order Transport

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CSC Group Workshop Falkensee



What is transport aka advection?

- Local effect.
- Propagation over time.

What's the problem with MOR for transport?

- State-space trajectory has no low-rank.
- Slow decay of singular values.

Hyperbolic Symptoms:

- Jacobian has real eigenvalues
- and is diagonalizable.

Numerical Medicine:

- CFL (Courant-Friedrichs-Lewy) condition
- SSP (Strong-Stability-Preserving) integrators



Hyperbolic PDE Examples:

- Advection Equation (1st Order Linear):

$$\frac{\partial u}{\partial t} = a \frac{\partial u}{\partial x}$$

- Wave Equation (2nd Order Linear):

$$\frac{\partial^2 u}{\partial t^2} = a \frac{\partial^2 u}{\partial x^2}$$

- (Inviscid) Burgers' Equation (Quasi-Linear):

$$\frac{\partial u}{\partial t} = u \frac{\partial u}{\partial x}$$

- (Isothermal) Euler Equations (Nonlinear):

$$\frac{\partial \rho}{\partial t} = - \frac{\partial q}{\partial x}$$

$$\frac{\partial q}{\partial t} = -a^2 \frac{\partial \rho}{\partial x} + b \frac{q|q|}{\rho} - g\rho \frac{\partial h}{\partial x}$$



1. Define center C : $\int_0^C [f(x)]^2 dt = \int_C^N [f(x)]^2 dt$.
 2. Determine center for each time step.
 3. Center trajectory around C .
-
- Computationally easy.
 - Theoretically low ranks possible.
 - Practically difficult.

¹S. Glavaski, J.E. Marsden, and R.M. Murray. **Model Reduction, Centering, and the Karhunen-Loeve Expansion**. Proceedings of the 37th IEEE Conference on Decision & Control: 2071–2076, 1998.

1. Linearize Model.
2. Determine inner product P for **some** $Q > 0$: $A^\top P + PA = -Q$.
3. Build linear reduced model:
 $A_r := U^\top PAU$, $B_r := U^\top PB$, $C := CU$.

- Computationally OK.
- Theoretically doable (works for linearized Euler equations).
- Practically what Q ?

²I. Kalashnikova, M.F. Barone, S. Arunajatesan and B.G. van Bloemen Waanders. **Construction of energy-stable projection-based reduced order models**. Applied Mathematics and Computation 249: 569–596, 2014.

1. Compute projections using a kernel method.
2. Mind the gap: Don't forget to center.
3. Construct ROM: Map to original space (Ay, there is the rub).
 - Computationally challenging (Solve large optimization problem).
 - Theoretically supported.
 - Practically maybe doable.

³J. Bouvrie and B. Hamzi. **Kernel Methods for the Approximation of Nonlinear Systems**. arXiv math.OA(1108.2903): 1–31, 2016.

Gas Transport Networks in MathEnergy:

- Large-Scale (10^4 , Many-Query)
- Hyperbolic (Conservation Laws)
- Nonlinear (Possibly Non-Differentiable)
- Descriptor System (Better Decoupling)

⁴Leia Organa after jumping down a garbage chute into a trash compactor on the death star.

All implemented model reduction techniques (#datadriven):

- Unstructured / Structured Empirical Cross Gramian
- Unstructured / Structured Empirical Balanced Truncation
- Unstructured / Structured Proper Orthogonal Decomposition
- Unstructured / Structured Dynamic Mode Decomposition

can all handle the previous hyperbolicity treatments.

⁵Raoul Duke on the edge of the desert when the drugs began to take hold.

Questions:

- Any war stories about MOR for hyperbolic systems?
- Enough redundancy in the networks to not care?
- Opinions or further methods?

P.S.: Other methods considered: Freezing, Shifted POD