



MAX PLANCK INSTITUTE
FOR DYNAMICS OF COMPLEX
TECHNICAL SYSTEMS
MAGDEBURG



COMPUTATIONAL METHODS IN
SYSTEMS AND CONTROL THEORY

About emgr

Christian Himpe

Computational Methods in Systems and Control Theory Group
Max Planck Institute Magdeburg

International Congress on Mathematical Software (ICMS 2020)

Session: “Accelerating Innovation Speed in Mathematics
by Trading Mathematical Research Data”

Supported by:



Federal Ministry
for Economic Affairs
and Energy



1. What is `emgr` (**EM**pirical **GR**amian Framework)?
2. Mathematical software as research data!



- Applied mathematics



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 - **Mathematical system theory**
 - Modern system theory by KALMAN (includes control theory)
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 - Efficient implementations
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 - **Computational science and engineering**
 - Modeling and discretization of engineering applications
 - Simulate, estimate, predict real-life behavior

General input-output system:

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Example: **Gas network model**

$$\begin{pmatrix} E_p & 0 \\ 0 & I \end{pmatrix} \begin{pmatrix} \dot{p} \\ \dot{q} \end{pmatrix} = \begin{pmatrix} 0 & A_{pq} \\ A_{qp} & 0 \end{pmatrix} \begin{pmatrix} p \\ q \end{pmatrix} + \begin{pmatrix} 0 & B_d \\ B_s & 0 \end{pmatrix} \begin{pmatrix} s_p \\ d_q \end{pmatrix} + \begin{pmatrix} 0 \\ f_q(p, q, s_p) \end{pmatrix}$$

$$\begin{pmatrix} s_q \\ d_p \end{pmatrix} = \begin{pmatrix} 0 & C_q \\ C_p & 0 \end{pmatrix} \begin{pmatrix} p \\ q \end{pmatrix}$$



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- Reachability (can the state be driven to any state by finite input?)
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- Use state trajectory data from (scaled) impulse responses.
- Impulse responses can also be computed for nonlinear systems!
- Observability can similarly be described by trajectory data.



Scoping emgr

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Reduced order model:

$$\dot{x}_r(t) = (V(A(Ux_r(t)))) + (V(Bu(t)))$$

$$\tilde{y}(t) = (C(Ux_r(t)))$$

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$$\dot{x}_r(t) = (VAU)x_r(t) + (VB)u(t)$$

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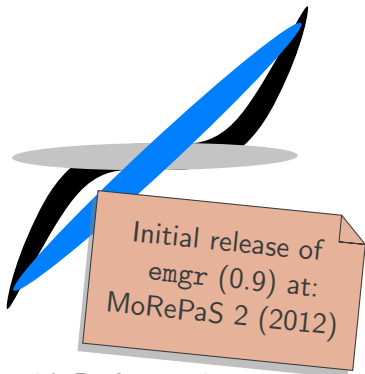
Empirical Gramians:

- Empirical Reachability Gramian
- Empirical Observability Gramian
- Empirical Linear Cross Gramian
- Empirical Cross Gramian
- Empirical Sensitivity Gramian
- Empirical Identifiability Gramian
- Empirical Joint Gramian

Features:

- Open-source **Octave** and **MATLAB** toolbox, with **Python** variant.
- Interfaces for: Solver, inner product kernels & low-rank computation.
- Configurable, vectorized and parallelizable.

More info: <https://gramian.de>





Through the lens of `emgr`



Classes of Software



- **Single-use software**
 - Computational proofs
 - Numerical experiments
 - Visualization generators

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- Version (semantic version vs. calendar version)



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- Language (*MATLAB File Exchange*)



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- RUNME (working example)
- CODE (code meta-data, i.e.: <https://github.com/gramian/code-ini>)



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- Test review
 - Developer defines and describes a test,
 - based on an analytically known solution,
 - or a solution computed by alternative means.
 - Reviewer evaluates test quality and result.



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→ document PDF & supplemental material zip archive
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- Programming language longevity
→ FORTRAN, LISP, MATLAB
- Programming language readability
→ MATLAB, MAPLE

Do you want to know more?

- Empirical Gramians: <https://gramian.de>
- Best Practices: <https://doi.org/bsb2>
- Sustainable Software: <https://arxiv.org/abs/1909.09469>
- Mathematical Software: <https://doi.org/10.1016/C2013-0-11363-3>

<https://himpe.science>

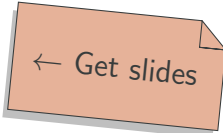
Acknowledgment:

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Do you want to know more?

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<https://himpe.science>

An orange sticky note with a folded top-right corner, containing the text '← Get slides'.

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