

System Order Reduction for Gas and Energy Networks

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► MathEnergy Project

Model Reduction Sub-Project:

- ▶ Nonlinear Model Reduction for Gas Networks (no linearization)
- ▶ Input-Output (boundary actuators and sensors)
- ▶ Data-Driven (“unsupervised learning” of system-theoretic operators)
- ▶ Projection-Based
- ▶ Software Deliverable (!)

→ **Platform for comparing model reduction for gas network simulation.**

C. Himpe, S. Grundel, P. Benner: **Model Order Reduction for Gas and Energy Networks**;
Journal of Mathematics in Industry 11: 13, 2021. doi:10.1186/s13362-021-00109-4

› About

MORGEN (Model Order Reduction for Gas and Energy Networks)

- ▶ High volatility due to green energy transition.
- ▶ Gas-fired power plants can compensate.
- ▶ Weather-dependent consumption **and** production (Power2Gas).

→ **Many simulations, every day, with a deadline.**

› About

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SORGEN (System Order Reduction for Gas and Energy Networks)

- ▶ Insufficient or sudden loss of supply.
- ▶ Ensuring supply of critical consumers.
- ▶ Increasing injection of biogas and hydrogen.

› Gas Network Modeling

Friction-Dominated 1D Isothermal Euler Equations:

$$\frac{1}{T_0 R_S z_0} \partial_t p = -\frac{1}{S} \partial_x q$$

$$\partial_t q = -S \partial_x p - \left(\overbrace{\frac{S g h_x}{T_0 R_S z_0}}^{\text{Gravity}} p + \overbrace{\frac{T_0 R_S z_0 \lambda_0 |q| q}{2 d S}}^{\text{Friction}} \frac{1}{p} \right)$$

1. Conservative interconnection (Kirchhoff laws)
2. Index reduction (Analytic)
3. Refinement strategy (CFL condition)
4. Spatial discretization (Finite differences)

Square Input-Output-System:

$$\begin{pmatrix} E_p(\theta) & 0 \\ 0 & E_q \end{pmatrix} \begin{pmatrix} \dot{p} \\ \dot{q} \end{pmatrix} = \begin{pmatrix} 0 & A_{pq} \\ \hat{A}_{qp} & 0 \end{pmatrix} \begin{pmatrix} p \\ q \end{pmatrix} + \begin{pmatrix} 0 & B_{pd} \\ B_{qs} & 0 \end{pmatrix} \begin{pmatrix} s_p \\ d_q \end{pmatrix} + \begin{pmatrix} 0 \\ f_q(p, q, \theta) \end{pmatrix}$$

$$\begin{pmatrix} s_q \\ d_p \end{pmatrix} = \begin{pmatrix} 0 & C_{sq} \\ C_{dp} & 0 \end{pmatrix} \begin{pmatrix} p \\ q \end{pmatrix}$$

› Spatial Discretizations

Identifier	Name	Index
ode_mid	Midpoint Discretization	0
ode_end	Endpoint Discretization	0

S. Grundel, N. Hornung, B. Klaassen, P. Benner, T. Clees: **Computing surrogates for gas network simulation using model order reduction**; in: Surrogate-based modeling and optimization: 189–212, 2013. 10.1007/978-1-4614-7551-4_9

S. Roggendorf: **Model order reduction for linearized systems arising from the simulation of gas transportation networks**; Master's thesis. University of Bonn; 2015.

› Spatial Discretization

Endpoint Discretization:

- ▶ Non-Normal (hyperbolic PDE model)
- ▶ Structured (two coupled variables)
- ▶ Nonlinear (friction, compressor, etc.)
- ▶ Parametric (temperature, specific gas constant)
- ▶ **Port-Hamiltonian** (allows approximate adjoint)

→ **Interesting** (challenging) **model reduction setting!**

› Temporal Discretizations

Identifier	Name	Order
imex1	Implicit-Explicit	1
imex2	Implicit-Explicit-Runge-Kutta	2
cnab2	Crank-Nicolson-Adams-Bashforth	2
ode23s	Rosenbrock	2
rk2hyp	Hyperbolic Runge-Kutta	2
rk4hyp	Hyperbolic Runge-Kutta	4
rk4	Classic Runge-Kutta	4

› Temporal Discretization

First Order Implicit Explicit:

- ▶ Explicit Euler combined with implicit Euler.
- ▶ Not a Runge-Kutta method.
- ▶ One nonlinear vector field evaluation.
- ▶ One linear problem (minimum for every solver).
- ▶ Matches spatial discretization order.

→ **Most efficient** (among tested) **time stepper!**

› Reductors

Identifier	Name	Type
pod	Proper Orthogonal Decomposition (POD)	Galerkin
gopod	Goal-Oriented POD	Galerkin
dspm	Dominant Subspace Projection Model Reduction	Galerkin
mpod	Modified POD	Oblique
bpod	Balanced POD	Petrov-Galerkin
bt	Balanced Truncation	Petrov-Galerkin
bg	Balanced Gains	Petrov-Galerkin
dmd	Dynamic Mode Decomposition Galerkin	Galerkin

› Reductor

General Findings:

- ▶ Galerkin methods much more stable than Petrov-Galerkin.
- ▶ Structure preserving (block-diagonal) projections necessary.
- ▶ Step input training for data-driven Gramian computation.
- ▶ Port-Hamiltonian property enables fast ROM computation.

Dominant Subspace Projection Model Reduction:

- ▶ Conjoins most reachable and most observable subspaces.
- ▶ Stability-preserving for considered (linearized) models.
- ▶ \mathcal{H}_2 error-bound and *a-priori* \mathcal{H}_2 error-indicator.

→ **Data-driven projection-based model reduction works here!**

› Software

MORGEN (Model Order Reduction for Gas and Energy Networks)

- ▶ **For engineers:** Test model reduction on your networks.
- ▶ **For mathematicians:** Test your model reduction on gas nets.
- ▶ **MATLAB & Octave** compatible
- ▶ **Open source** licensed
- ▶ **Version 1.2** upcoming



<https://git.io/morgen>

› Experimental Design

- ▶ Generic training input (step)
- ▶ Designed or random test scenarios
- ▶ Short training periods (1–12h)
- ▶ Long testing periods (24h)
- ▶ Generic training parameter sampling (sparse grid)
- ▶ Random test parameter sampling (uniform distributed)

Evaluation:

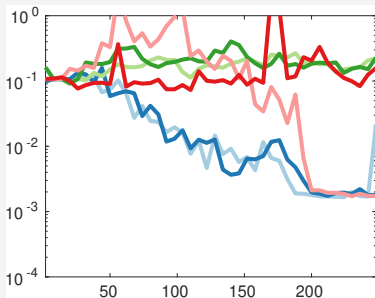
- ▶ Relative $L_2 \otimes L_2$ model reduction output error
- ▶ **MORscore** benchmark scoring

› Chinese Transport Network

- ▶ ≈ 8600 km Total length
- ▶ 5 Inflow nodes
- ▶ 3 Outflow nodes
- ▶ 38 Compressor stations

From: L. Jin, A.K. Wojtanowicz: **Optimization of Large Gas Pipeline Network – A Case Study in China**;
Journal of Canadian Petroleum Technology 49(4): 36–43, 2010.
L. Jin, A.K. Wojtanowicz: **Optimization of Large Gas Pipeline Network in China – a Feasibility Study**;
Canadian International Petroleum Conference: 174, 2008.

► Numerical Results



- Struct. Proper Orthogonal Decomposition (WR)
- Struct. Empirical Dominant Subspaces (WR + WR*)
- Struct. Empirical Dominant Subspaces (WX*)
- Struct. Empirical Dominant Subspaces (WZ*)
- Struct. Goal-Oriented POD (WR)
- Struct. Dynamic Mode Decomposition Galerkin (WR)

MORscores: $\mu \in [0, 1)$

POD (WR) 0.12

DSPMR (WR + WR*) 0.12

DSPMR (WX*) 0.05

DSPMR (WZ*) 0.04

GOPOD (WR) 0.07

DMD Galerkin (WR) 0.06

› Summary

Recommended Ensemble:

- ▶ Model: **pH** (port-Hamiltonian Endpoint Discretization)
- ▶ Application: **Gas** (Gas Transport Pipeline Network)
- ▶ Solver: **IMEX** (1st Order Implicit Explicit Time Stepper)
- ▶ Reductor: **DSPMR** (Dominant Subspace Projection Model Reduction)
- ▶ Software: **MORGEN** (Model Order Reduction for Gas and Energy Networks)

<https://doi.org/gndbmv> (Paper)

<https://git.io/morgen> (Code)

<https://himpe.science> (Slides)

